

# Ergodic Theory and Measured Group Theory

## Lecture 12

### An example.

$$S := \{a, a^{-1}, b, b^{-1}\} \quad \pi := \left(\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}\right)$$

$$P := \begin{array}{c} \begin{array}{ccc} & a & a^{-1} & b & b^{-1} \\ \begin{array}{c} a \\ a^{-1} \\ b \\ b^{-1} \end{array} & \begin{pmatrix} \frac{1}{3} & 0 & \frac{1}{3} & \frac{1}{3} \\ 0 & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & 0 \\ \frac{1}{3} & \frac{1}{3} & 0 & \frac{1}{3} \end{pmatrix} \end{array} \end{array}$$

The induced Markov measure is supported on  $\mathbb{T}^2$  and this

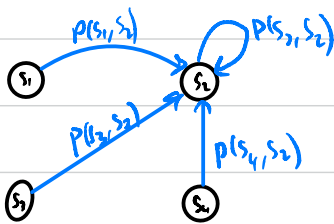
is what was used in the Gromov-Meyer theorem.

### Stationarity.

Let  $S$  be a state space and  $\pi, P$  as before.

We think of the Markov chain as a random walk on  $S$ , where we start with  $s \in S$  with probability  $= \pi(s)$  and move to  $s'$  with prob.  $P(s, s')$ .

Thus,  $\pi$  is the initial distribution. What's the distribution after one step, i.e. after one step, what's the prob that we are in  $s \in S$ ?



$$\begin{aligned} \mathbb{P}[\omega_1 = s] &= \sum_{\omega_0 \in S} \pi(\omega_0) \cdot P(\omega_0, s) \\ &= \pi(s) \end{aligned}$$

$$\text{Hence } \pi_1 = \pi \cdot P$$

$$\text{after two steps: } \pi_2 = \pi_1 \cdot P = \pi P^2 \dots$$

Def. The Markov chain given by  $(\pi, P)$  is stationary if  $\pi = \pi \cdot P$ . Equiv., the distribution at what state the walk is doesn't change.

Markov measure on  $S^{\mathbb{N}}$ .

A Markov chain on a state space  $S$ , denoted by  $m$ , is a prob measure on each  $S^n$ . For any basic clopen set  $[\omega]$ , where  $\omega \in S^{\mathbb{N}}$ , define  $IP_m[\omega] := m(\omega)$ .

Then  $IP_m[\omega] = \sum_{s \in S} IP_m[\omega s]$ , which shows that  $IP_m$

is a  $\checkmark$  probability premeasure on the algebra of clopen sets, hence extends to a prob measure on all Borel sets by Caratheodory's theorem.

Recall that shift  $s: S^{\mathbb{N}} \rightarrow S^{\mathbb{N}}$  is a Borel function and we want to understand when a Markov measure on  $S^{\mathbb{N}}$  is  $s$ -invariant.

Prop. A Markov measure  $IP_m$  on  $S^{\mathbb{N}}$  is stationary  $\Leftrightarrow$  it is shift-invariant.

Proof. Take a basic set  $[\omega]$  and note that  $s^{-1}[\omega] = \bigcup_{t \in S} [t\omega]$ .

It's an exercise to show that  $\mathbb{P}_m(S^{-1}[w]) = \sum_{t \in S} \mathbb{P}_m([tw])$   
 $\Leftrightarrow \pi P = \pi$ . □

Def. A stochastic matrix  $P$  (i.e. rows add-up to 1 and non-negative) is called **irreducible** if the prob. of transitioning from any  $a \in S$  to any  $b \in S$  in some number of steps is positive, i.e.  $P^k(a, b) > 0$  for some  $k \geq 1$ .

Prop. A Markov measure on  $S^{\mathbb{N}}$  is shift-invariant and ergodic  
 $\Leftrightarrow \pi P = \pi$  and  $P$  is irreducible.

Birkhoff's theorem (2000). Let  $\mathbb{T}_d = \langle S \rangle_{d < \infty}$  and let  $\mu$  be a Markov measure on  $S^{\mathbb{N}}$  that is strictly irreducible and stationary. Then for every  $\mu$ -a.s. action of  $\mathbb{T}_d$  on  $(X, \mu)$ , every  $f \in L^1(X, \mu)$ ,

$$\lim_{n \rightarrow \infty} \frac{\sum_{g \in B_n} f(\tau \cdot x) \mu(g)}{m(B_n)} = \mathbb{E}(f : \mathcal{B}_{\text{inv}}) \text{ a.e.}$$

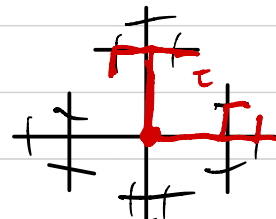
$m(B_n) = n + 1$

This generalizes the Birkhoff-Ergodic theorem. Moreover, the actual

statement is for actions of free semigroup (freely generated).

Theorem (Zornick-Ts). Let  $\mathbb{F}_d := \langle S \rangle$ , where  $d \geq 2$  and  $S$  is the standard symmetric set of generators.

Let  $m$  be a stationary Markov measure on  $S^{\mathbb{N}}$ , supported on  $\mathbb{F}_2$  exactly. Then for any pump action of  $\mathbb{F}_d$  on  $(X, \mu)$  and any  $f \in L^1(X, \mu)$ ,

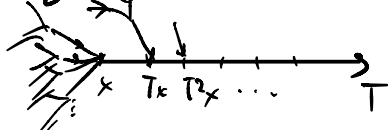
$$\lim_{m(\tau) \rightarrow \infty} \frac{\sum f(g \cdot x) \cdot m(g)}{m(\tau)} = E(f | B_{\text{inv}}) \quad \text{a.e.}$$


where  $\tau$  ranges over  $\bigwedge_{\text{finite}}$  subtrees of  $\text{Cay}(\mathbb{F}_d, S)$  containing the identity.

This is implied by our backward ergodic theorem but we will now try to state.

Backward ergodic theorem. Let  $T$  be a cbl-to-one pump transformation on  $(X, \mu)$ . Recall that the classical ptwise erg theorem says that  $\forall f \in L^1(X, \mu)$ , for a.e.  $x \in X$ ,

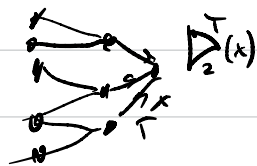
$$\lim_{n \rightarrow \infty} \text{average of } f \text{ over } \mathcal{I}_n^T \cdot x = E(f | B_T).$$



## Backward $\Delta$ theorem.

$\lim_{h \rightarrow 0}$  weighted average of  $f$  over  $\Delta_h^T(x) = \mathbb{E}(f | \mathcal{B}_T)$ ,

where  $\Delta_h^T(x) = \{x\} \cup T^{-1}x \cup \dots \cup T^{-n}x$ .



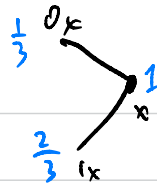
What are the weights? By the Luzin - Novikov uniformization theorem (learn DST!), there are Borel right inverses  $(\gamma_n)_{n \in \mathbb{N}}$  to  $T$  s.t.  $T^{-1}(x) = \{\gamma_n x : n \in \mathbb{N}\}$ , E.g. in case of  $T$  being the shift on  $\mathbb{Z}^d$ ,  $\gamma_0(x) := 0x$  and  $\gamma_1(x) := 1x$ . These  $\gamma_n$  are not measure preserving, but we may assume WLOG (learn DST!) that  $\gamma_n \# \mu \ll \mu$ . Thus, there is a Radon-Nikodym derivative  $\frac{d\gamma_n \# \mu}{d\mu}(x)$  which we treat as the weight of  $\gamma_n x$  relative to  $d\mu_x$ . That gives a Borel function  $w: E_T \rightarrow \mathbb{R}^+$  mapping  $(x, y) \mapsto w_x(y)$  satisfying

$w_x(y) \cdot w_y(z) = w_x(z)$ . Thus  $w$  corrects the noninvariance of  $\mu$  under the right-inverses:

$$\mu(\gamma_n(A)) = \int_A w_x(\gamma_n x) d\mu(x).$$

This  $w$  is called the Radon-Nikodym cocycle of  $E_T$  with respect to  $\mu$ . E.g. for the shift  $s$  on  $\mathbb{Z}^d$  with  $\mu := \left\{ \frac{1}{3}, \frac{1}{3} \right\}$ ,

$$\omega_x(0x) = \frac{1}{3} \quad \& \quad \omega_x(1x) = \frac{2}{3}$$



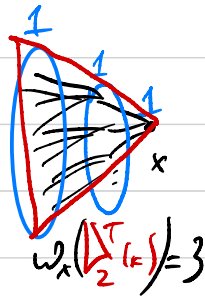
In the above theorem,

$$\text{weighted-average of } f \text{ over } \Delta_n^T(x) := \frac{\sum_{y \in \Delta_n^T(x)} f(y) \cdot \omega_x(y)}{\omega_x(\Delta_n^T(x))}$$

$$\text{Because } T \text{ preserves } \mu, \quad \sum_{y \in T^{-1}(x)} \omega_x(y) = 1.$$

Thus,  $\omega_x(\Delta_n^T(x)) = n+1$ . Then:

$$\lim_{n \rightarrow \infty} \frac{1}{n+1} \sum_{y \in \Delta_n^T(x)} f(y) \cdot \omega_x(y) = \mathbb{E}(f | \mathcal{B}_T).$$



Backward ergodic with trees. ... for a.e.  $x$ , let  $\tau_x$  range over tree behind  $x$  (in the direction of  $T^{-1}$ ) rooted at  $x$ , then:

$$\lim_{\omega_x(\tau_x) \rightarrow \infty} \frac{\sum_{y \in \tau_x} f(y) \omega_x(y)}{\omega_x(\tau_x)} = \mathbb{E}(f | \mathcal{B}_T).$$